## Lecture II: Charlier's theory

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## Equations for preliminary orbits

From the geometry of the observations we have

$$
\begin{equation*}
r^{2}=\rho^{2}+2 q \rho \cos \epsilon+q^{2} \quad \text { (geometric equation). } \tag{1}
\end{equation*}
$$

From the two-body dynamics, both Laplace's and Gauss' methods yield an equation of the form

$$
\begin{equation*}
\mathcal{C} \frac{\rho}{q}=\gamma-\frac{q^{3}}{r^{3}} \quad \text { (dynamic equation) } \tag{2}
\end{equation*}
$$

with $\mathcal{C}, \gamma$ real parameters depending on the observations.

## Preliminary orbits and multiple solutions

intersection problem:

$$
\left\{\begin{array}{l}
(q \gamma-\mathcal{C} \rho) r^{3}-q^{4}=0  \tag{3}\\
r^{2}-q^{2}-\rho^{2}-2 q \rho \cos \epsilon=0 \\
r, \rho>0
\end{array}\right.
$$

reduced problem:

$$
\begin{equation*}
P(r)=0, \quad r>0 \tag{4}
\end{equation*}
$$

with
$P(r)=\mathcal{C}^{2} r^{8}-q^{2}\left(\mathcal{C}^{2}+2 \mathcal{C} \gamma \cos \epsilon+\gamma^{2}\right) r^{6}+2 q^{5}(\mathcal{C} \cos \epsilon+\gamma) r^{3}-q^{8}$.
We investigate the existence of multiple solutions of the intersection problem.

## Charlier's theory



## Carl V. L. Charlier (1862-1934)

In 1910 Charlier gave a geometric interpretation of the occurrence of multiple solutions in preliminary orbit determination with Laplace's method, assuming geocentric observations $(\gamma=1)$.
the condition for the appearance of another solution simply depends on the position of the observed body' (MNRAS, 1910)

Charlier's hypothesis: $\mathcal{C}, \epsilon$ are such that a solution of the corresponding intersection problem with $\gamma=1$ always exists.

## Charlier's theory

A spurious solution of (4) is a positive root $\bar{r}$ of $P(r)$ that is not a component of a solution ( $\bar{r}, \bar{\rho}$ ) of (3) for any $\bar{\rho}>0$.

We have:

- $P(q)=0$, and $r=q$ corresponds to the observer position;
- $P(r)$ has always 3 positive and 1 negative real roots.

Let $P(r)=(r-q) P_{1}(r)$ : then

$$
P_{1}(q)=2 q^{7} \mathcal{C}[\mathcal{C}-3 \cos \epsilon] .
$$

If $P_{1}(q)<0$ there are 2 roots $r_{1}<q, r_{2}>q$; one of them is spurious.
If $P_{1}(q)>0$ both roots are either $<q$ or $>q$; they give us 2 different solutions of (3).

## Zero circle and limiting curve

zero circle: $\mathcal{C}=0$,
limiting curve: $\mathcal{C}-3 \cos \epsilon=0$.


The green curve is the zero circle. The red curve is the limiting curve, whose equation in heliocentric rectangular coordinates $(x, y)$ is

$$
4-3 \frac{x}{q}=\frac{q^{3}}{r^{3}} .
$$

## Geometry of the solutions



The position of the observed body corresponds to the intersection of the level curve $\mathcal{C}^{(1)}(x, y)=\mathcal{C}$ with the observation line (defined by $\epsilon$ ), where $\mathcal{C}^{(1)}=\mathcal{C}^{(1)} \circ \Psi$, $\mathcal{C}^{(1)}(r, \rho)=\frac{q}{\rho}\left[1-\frac{q^{3}}{r^{3}}\right]$ and $(x, y) \mapsto \Psi(x, y)=(r, \rho)$ is the map from rectangular to bipolar coordinates.

Note that the position of the observed body defines an intersection problem.

## The singular curve



The singular curve is the set of tangency points between an observation line and a level curve of $\mathcal{C}^{(1)}$. It can be written as

$$
4-3 q \frac{x}{r^{2}}=\frac{r^{3}}{q^{3}} .
$$

## Multiple solutions: summary



Alternative solutions occurs in 2 regions: the interior of the limiting curve loop and outside the zero circle, on the left of the unbounded branches of the limiting curve.

## Generalized Charlier's theory

See Gronchi, G.F.: CMDA 103/4 (2009)
Let $\gamma \in \mathbb{R}, \gamma \neq 1$. By the dynamic equation we define

$$
\mathfrak{C}^{(\gamma)}=\mathcal{C}^{(\gamma)} \circ \Psi, \quad \mathcal{C}^{(\gamma)}(r, \rho)=\frac{q}{\rho}\left[\gamma-\frac{q^{3}}{r^{3}}\right]
$$

with $(x, y) \mapsto \Psi(x, y)=(r, \rho)$.
We also define the zero circle, with radius

$$
r_{0}=q / \sqrt[3]{\gamma}, \quad \text { for } \gamma>0 .
$$

Introduce the following assumption:
the parameters $\gamma, \mathcal{C}, \epsilon$ are such that the corresponding intersection problem admits at least one solution.

## Topology of the level curves of $\mathcal{C}^{(\gamma)}$



## Topology of the level curves of $\mathrm{C}^{(\gamma)}$


$0<\gamma<1$

$\gamma>1$

## The singular curve

For $\gamma \neq 1$ we cannot define the limiting curve by Charlier's approach, in fact $P(q) \neq 0$. Nevertheless we can define the singular curve as the set
$\mathcal{S}=\{(x, y): \mathcal{G}(x, y)=0\}, \quad \mathcal{G}(x, y)=-\gamma r^{5}+q^{3}\left(4 r^{2}-3 q x\right)$.

$\gamma \leq 0$

$0<\gamma<1$

$\gamma>1$

## An even or an odd number of solutions

The solutions of an intersection problem (3) can not be more than 3. In particular, for $(\gamma, \mathcal{C}, \epsilon)$ fulfilling (5) with $\gamma \neq 1$, if the number of solutions is even they are 2, if it is odd they are either 1 or 3.
For $\gamma \neq 1$ we define the sets

$$
\mathcal{D}_{2}(\gamma)= \begin{cases}\emptyset & \text { if } \gamma \leq 0 \\ \left\{(x, y): r>r_{0}\right\} & \text { if } 0<\gamma<1 \\ \left\{(x, y): r \leq r_{0}\right\} & \text { if } \gamma>1\end{cases}
$$

and

$$
\mathcal{D}(\gamma)=\mathbb{R}^{2} \backslash\left(\mathcal{D}_{2}(\gamma) \cup\{(q, 0)\}\right)
$$

Points in $\mathcal{D}_{2}(\gamma)$ corresponds to intersection problems with 2 solutions; points in $\mathcal{D}(\gamma)$ to problems with 1 or 3 solutions.

## Residual points


b)

Fix $\gamma \neq 1$ and let $(\bar{\rho}, \bar{\psi})$ correspond to a point $\mathrm{P} \in \mathfrak{S}=\mathcal{S} \cap \mathcal{D}$. Let

$$
F(\mathcal{C}, \rho, \psi)=\mathcal{C} \frac{\rho}{q}-\gamma+\frac{q^{3}}{r^{3}}, \quad r=\sqrt{\rho^{2}+q^{2}+2 \rho q \cos \psi}
$$

If $F_{\rho \rho}(\mathcal{C}, \bar{\rho}, \bar{\psi}) \neq 0$, we call residual point related to P the point $\mathrm{P}^{\prime} \neq \mathrm{P}$ lying on the same observation line and the same level curve of $\mathcal{C}^{(\gamma)}(x, y)$, see Figure a).
If $F_{\rho \rho}(\mathcal{C}, \bar{\rho}, \bar{\psi})=0$ we call P a self-residual point, see Figure b).

## The limiting curve

Let $\gamma \neq 1$. The limiting curve is the set composed by all the residual points related to the points in $\mathfrak{S}$.


## The limiting curve

Separating property: the limiting curve $\mathcal{L}$ separates $\mathcal{D}$ into two connected regions $\mathcal{D}_{1}, \mathcal{D}_{3}: \mathcal{D}_{3}$ contains the whole portion $\mathfrak{S}$ of the singular curve. If $\gamma<1$ then $\mathcal{L}$ is a closed curve, if $\gamma>1$ it is unbounded.


$$
(\gamma \leq 0)
$$

## The limiting curve

Transversality: the level curves of $\mathrm{C}^{(\gamma)}(x, y)$ cross $\mathcal{L}$ transversely, except for at most the two self-residual points and for the points where $\mathcal{L}$ meets the $x$-axis.

Limiting property: For $\gamma \neq 1$ the limiting curve $\mathcal{L}$ divides the set $\mathcal{D}$ into two connected regions $\mathcal{D}_{1}, \mathcal{D}_{3}$ : the points of $\mathcal{D}_{1}$ are the unique solutions of the corresponding intersection problem; the points of $\mathcal{D}_{3}$ are solutions of an intersection problem with three solutions.

## Multiple solutions: the big picture



